

Precision – Multi-Turn – Sensor DMG24 / xx M Ze

Output signal 0/4...20mA, 0...10V, central fixing M10 x 0,75, xx = 3,-5- or 10-turn maintenance-free sliding bearing, option IP65, for mechanical adjustment



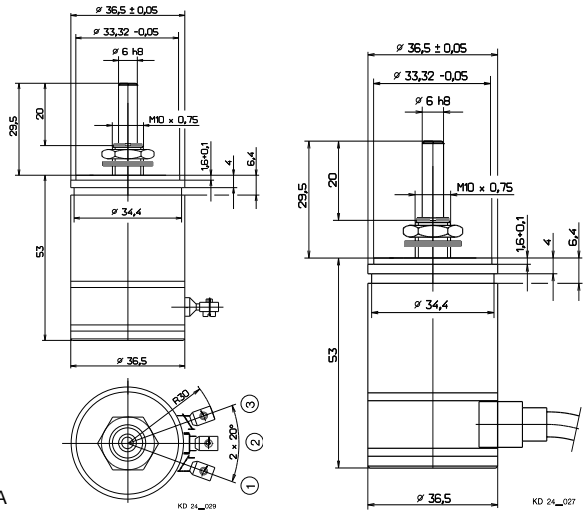
The Precision – Multi-Turn Potentiometer DMG24 is used as actual value transmitter for machinery and plant engineering as well as setpoint adjuster and actual value transmitter for apparatus construction and toolbuilding.

options

- protection class IP65
- shaft u. central fixing in inch
- terminal wires
- output signal rising counterclockwise

mechanical data of the potentiometer

- housing.....: aluminium
- shaft.....: noble metal $\varnothing 6^{h9}$
- bearing.....: maintenance-free sliding bearing
- resistor element.....: precision wire winding or hybrid
- slider tap / wiper tap.....: single
- housing protection.....: IP 60
- class.....: according to table
- type of connection.....: central fixing M10 x 0,75
- mounted by.....: according to table +10°
- mechanical rotation angle.....: according to table
- electrical rotation angle.....: max. 120 rpm
- rotation speed.....: to 0,8 Ncm
- torque.....: according to table
- rotation load life.....



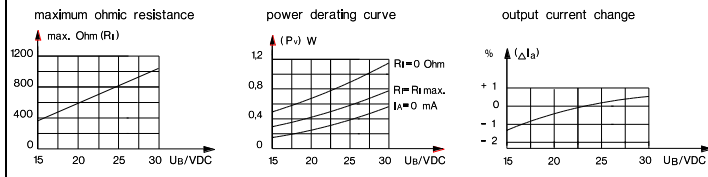
electrical data of the potentiometer

- output signal.....: 0/4...20 mA $\pm 0,04$ mA, 0...10 V $\pm 0,03$ V
- resistance tolerance.....: $\pm 5\%$ precision wire, $\pm 10\%$ hybrid element
- linearity tolerance.....: $\pm 0,25\%$
- insulation resistance.....: 1000 M-Ohm
- test voltage.....: 1000 V
- power rating.....: according to table
- slider load current.....: precision wire max. 20mA, hybrid element max.10mA
- temperature range.....: -25°C till +80°C
- temperature coefficient.....: precision wire winding 50 ppm/°C, hybrid 100 ppm/°C

electrical data of transducer

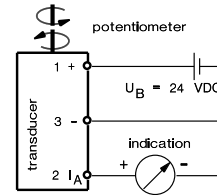
- operating voltage U_B: + 24 VDC -5% + 25% internal resistance.. R_i: ≤ 1 M Ω
 max. ripple of U_B: 2,5 V_{SS} linearity error max.....: $\pm 0,5\%$
 total current.....: ca. 16 mA + I_A
 output current.. I_A: 0...20 mA / 4...20 mA temperature coefficient of output current.....: $\leq 0,3 \times 10^{-3}/K$
 output voltage U_A: 0...10 V
 residual current.. I_A: ≤ 10 μA
 output current ripple
 ripple at 10% U_B: $\leq 0,3\%$ power derating at 80°C amb.temperature $P_{V...}$: 0,9 W
 ripple at 2% U_B: $\leq 0,1\%$ $\leq 60^\circ C$ amb.emperature $P_{V...}$: 1,2 W
 burden resistance storage temperature $T_{U...}$: - 55 till + 150° C
 at U_B 24 V - 5%..... R_L: max. 500 Ω operating temperature $T_{U...}$: - 25 till + 80° C

Key electrical data of the transducer



mA 3-wire

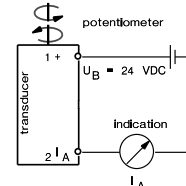
terminal plan 0/4...20 mA



line verification			
electrical connection	point	term.	colour
operating voltage	1	+	brown
output current	2	I _A	white
zero VDC	3	-	green

mA 2-wire

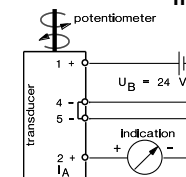
terminal plan 0/4...20 mA



line verification			
electrical connection	point	term.	colour
signal input	1	+	brown
signal output	2	I _A	white

mA 4-wire

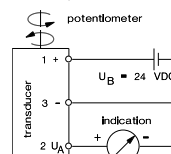
terminal plan transducer 0/4...20 mA



Nr.	colour	function
1	brown	operating voltage
2	white	output current
4	green	zero VDC
5	green	zero VDC

VDC 3-wire

terminal plan



line verification			
electrical connection	point	term.	colour
operating voltage	1	+	brown
output current	2	U _A	white
zero VDC	3	-	green

Type	Turn (rotation angle)	Watt	rotation load life
DMG 24 / 10 M Ze DMG 24 / 10 M Ze Hy	10 – turn (3600°)	2,0	1 x 10 ⁶ 5 x 10 ⁶
DMG 24 / 05 M Ze	5 – turn (1800°)	1,5	5 x 10 ⁵
DMG 24 / 03 M Ze	3 – turn (1080°)	1,0	3 x 10 ⁵

output signal				
	mA 3-wire	mA 2-wire	mA 4-wire	VDC 3-wire
clamp connection	0...20mA 4...20mA	4...20mA	possible	0...10VDC
cable connection	0...20mA 4...20mA	4...20mA	possible	0...10VDC
terminal block	0...20mA 4...20mA	4...20mA	possible	0...10VDC

*1 Hy = resistor element in Hybrid Technology
 *2 Standard rotation direction: right

For your information!

Please note that because of missing material availability the wiper could be C7521 material instead of C7701. 25.08.22

Sheet #: Ke2440

Amendment / Print: 29.08.22 / 29.08.22